# High performance probe with controller

## **GYMR5** Probe

## **RS422**

## High performance pan cake type



GYMR5 probe is the pan cake type which put the thickness of the head part in 36mm. Applying to hydraulic cylinder, its total length becomes space saving. Between probe and controller, RS-422 differential line driver transmission, providing robustness against electrical noise, is used. In combination with a digital output controller, Min.1  $\mu$  m resolution is possible. Please consider GYMR6 (page 34-35) in a new inquiry.

## Specifications

	Non-linearity	≦±0.025%FS TYP	
Accuracy	Resolution	(analogue)16bit(with GYHC)	
nuc.		(digital) Min.1 $\mu$ m (with GYDC-05)	
асу	Repeatability	≦±0.001%FS	
Ì	Temp. drift	≦±20ppmFS/°C	
	Max. Pressure	35MPa(probe rod)	
Εŋ	Operating temp.	−20°C~+80°C	
iro	Storage temp.	-40°C∼+80°C	
mm	Vibration	6G(40Hz 2mmPP)	
Environment	Shock	100G(2msec)	
	IP grade	IP64	

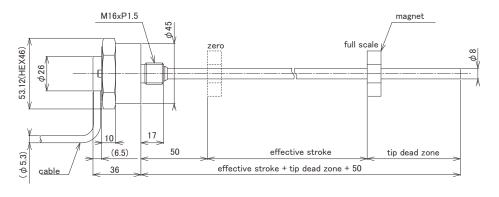
- •The above mentioned accuracy applies to sensors with an effective stroke of 300mm or more.
- •The specification of stroke less than 300mm is equal that of stroke 300mm.

#### ♦associated controller

- \*analogue output:GYHC(page 50-51), GYFC2\*3(page 52-53)
- •digital output: GYDC-S1 (page 54-55), GYDC-05 (page 56-57)

#### **Dimensions**

#### ■Probe



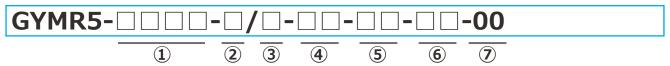
#### ■ Cable

Cable color	Function			
red	Sensor power			
white	0V			
green	Start(+)			
black	Stop(+)			
blue	Start(-)			
brown	Stop(-)			

 shield should be connected to shield terminal of the controller.

- •Material probe head: SS304, probe rod: SS304
- \*magnet : Select one from group GG on page 109
- ${}^{\scriptscriptstyle \bullet}\text{The tip}$  dead zone length depends on the selected magnet or float.

## ■ Probe



#### **1** Effective stroke

15mm~2000mm

#### 2 Head dead zone

S:50mm(STD)

□: □mm(option)(specified by customers)

•Possible Min. length depends on the selected magnet or float.

### **3Tip dead zone**

S:70mm/90mm/100mm(STD)

•S (STD length) depends on the selected magnet or float in  $(\bar{5})$ .

tip DZ	magnet	float
70mm	M2PN, M0SM, M0LM,	F25N, F28N
	M3, M11N	
90mm		F28S, F30S
100mm	T144, T163	F40S, F42S, F50S, F54S

☐: ☐mm(option)(specified by customers)

#### **4**Thread/Rod diameter

K8 : M16xP1.5, rod Φ8(STD)M : M24xP1.0, rod Φ10N : M18xP1.5, rod Φ10

\*In case of stroke longer than 1000mm, rod  $\Phi\,10$  is recommended.

#### **5** Associated magnet or float

<float> <magnet> M2PN: No.2PN (STD) : Ф28 SS316L F28S M0SM : No. ΦSPM F30S Ф30 SS316L M0LM : No.ΦLPM F40S Ф40 SS316(B) M3 : No.3 F42S Ф 42.5 SS316 M11N : No.11N : Ф50 SS316L F50S : Ф54 SS304 : No.T14-M4 F54S T144 T163 : No.T16-M3 F25N :RF-A10 plastic :RF-A6 plastic

- •Please consult if you select a magnet or a float of other than above.
- •This Model code means only specifying associated magnet or float.
- •When you need a magnet or float, please order separately.

#### **6** Cable connection

 $\triangle G \square F$ : pigtail / cable end : free

 $\Delta G \square A$ : pigtail / cable end : with connector for relay  $\Delta G \square FC$ : pigtail / cable end : with connector for GYFC2/3

 $(\Box : cable length(m), Max.10m)(*)$ 

(∆:cable type

S:standard, R:robot cable)

(\*) In case of using extension cable sensor cable (m) + extension cable (m)  $\leq$  200m

•Please consider extension cable on page 111.

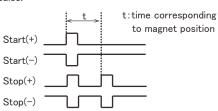
### **7**Output

00: depends on external controller

## [Start/Stop-Interface]

#### ◆In case of using probe only,

probe outputs digital signals (start/stop) using RS422 differential line drivers. In response to user's interrogation (start) pulse, probe provides stop pulse.



<sup>·</sup>Possible Min. length depends on the selected magnet or float.