

GYSE-A-PF Probe

Analogue



High performance analogue output (detachable probe element)



This is the linear profile version of GYSE-A. It is a high performance analog output probe, and has the high resolution of 16bit. It has also velocity output. Using two pcs of magnet on the probe as another option, detecting each magnet position or relative distance between the two is possible. The inside probe element can be detached from the outer housing, and with the captive software (GPM), zero and gain adjustment is possible at user side.

Specifications

Accuracy	Non-linearity	$\leq \pm 0.025\% \text{FS TYP}$
	Resolution	16bit (1/65536)
	Repeatability	$\leq \pm 0.001\% \text{FS}$ (Min. $\pm 3 \mu \text{m}$)
	Temp. drift	$\leq \pm 20 \text{ppmFS}/^\circ\text{C}$
Output	Position (STD)	0~10V (output current : Max.5mA, load : Min.2k Ω) or 4~20mA (load : Max.500 Ω)
	Velocity (Option)	$\pm 10\text{V}$ (output current : Max.5mA, load : Min.2k Ω) or 4~20mA (load : Max.500 Ω)
	Alarm	Open drain 50V 0.1A (for magnet missing)
	Power supply	+24(± 2)VDC (70mA)
Sampling freq.		Std 1kHz (total body length : up to 1250mm)
Environment	Operating temp.	-20 $^\circ\text{C}$ ~+75 $^\circ\text{C}$
	Storage temp.	-40 $^\circ\text{C}$ ~+75 $^\circ\text{C}$
	Vibration	15G (20~100Hz)
	Shock	100G (2msec)
	IP grade	IP65

- The above mentioned accuracy applies to sensors with an effective stroke of 300mm or more.

- The specification of stroke less than 300mm is equal that of stroke 300mm.

(*) Sampling frequency : Max. 3.75kHz (It depends on the total body length (shows in Model (8)), and the consumption current increases.)

- Fixing clamps are supplied.

stroke < 600mm: 2 pcs

600~1000mm:3 pcs

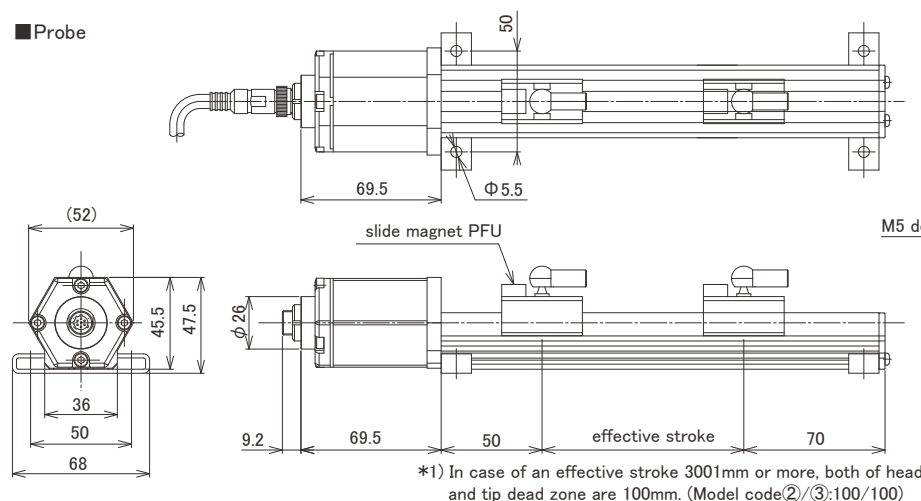
1001~1200mm: 4 pcs

1501 ~ 2000mm: 5 pcs

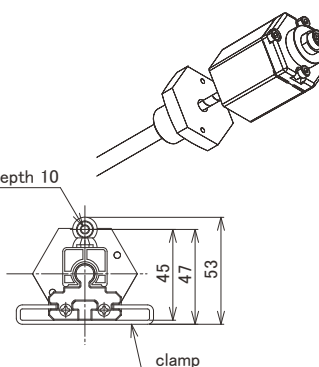
One clamp is added every 500mm

Dimensions

■ Probe



■ detachable probe element

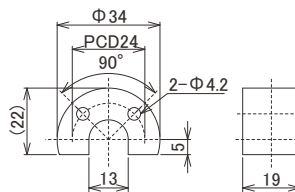
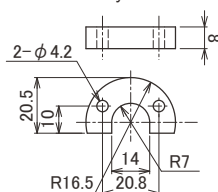
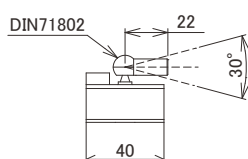


■ magnet

slide magnet
model:PFU
materials:polyacetal

floating magnet
model: No.5N-UK
materials: MC nylon

floating magnet
model: No.5PFT-LG
materials: SS304



■ Cable

Cable color	Pin number	Function
red	1	+24VDC
while	2	0V
blue	3	OUT1
green	4	COM1
brown	5	OUT2
black	6	COM2
yellow	7	Alarm

- shield should be connected to FG of user's unit.

- materials ; Probe head : Al alloy, body : Al alloy
- connector ; straight or L-sharped (housing parts : BS with Ni plating)
- Applied cable diameter: $\Phi 6.6 \sim \Phi 7.5$, Wire size : 0.5mm²
- cable length : Max.10m (0~10V output), Max.100m (4~20mA output)

■ Probe

GYSE-A-□□□□-□/□-PF-□□-□□-□/□-□-□

① ② ③ ④ ⑤ ⑥ ⑦ ⑧ ⑨

① Effective stroke

15~7500mm

② Head dead zone

S: 50mm (STD)

□: □mm (option) (specified by customers)

• Possible Min. length depends on the selected magnet.

③ Tip dead zone

S: 50mm (STD)

□: □mm (option) (specified by customers)

• Possible Min. length depends on the selected magnet.

④ Associated magnet

PFU : PFU slide magnet
FE : No.5N-UK
BP : No.5PFT-LG

• Please consult if you select a magnet of other than above.
• This Model code means only specifying associated magnet.
• When you need a magnet, please order separately.

⑤ Cable connection

CN: connector (STD)

△G□F: pigtail / cable end : free

△G□A: pigtail / cable end : with connector for relay

(□: cable length (m), Max.10m) (*)

(△: cable type

S: standard, H: high temp. cable, R: robot cable)

(*) In case of using extension cable

Voltage output : sensor cable (m) + extension cable (m) ≤ 10m

Current output : sensor cable (m) + extension cable (m) ≤ 100m

• Please consider extension cable on page 112.

• In case that you need loose mating connector, ordering connector (straight or L-shaped) separately is necessary.

⑥ Position output (OUT1)

AD: 0~10V (When magnet moves toward tip, output increase)

AR: 10~0V (When magnet moves toward tip, output decrease)

BD: 4~20mA (When magnet moves toward tip, output increase)

BR: 20~4mA (When magnet moves toward tip, output decrease)

CD□□: bipolar output (-□V~+□V)

(for example CD10: -10V~+10V)

CR□□: bipolar output (+□V~-□V)

(for example CR05: +5V~-5V)

V Z/F: option (specified voltage)

(for example V1/5: 1~5V, V9.5/0.5: 9.5~0.5V)

I Z/F: option (specified current)

(for example I5.2/20: 5.2~20mA, I18/5: 18~5mA)

[Z=output at zero position, F=output at full position]

⑦ Option : Analogue output (OUT2)

• N: without option (STD)

• Position output: select from ⑥

• Velocity output (Note1)

VA[]: ±10V

WB[]: 4~20mA

[]: max. velocity (1.00~999 mm/s)

<ex.9R99 : max. velocity = 9.99 mm/s>

(Note1)

VA : When magnet stops, output is 0V.

When moving toward probe tip, +10V.

WB : When magnet stops, output is 4mA.

When moving in any direction, 20mA.

⑧ Option

blank: without option

X2: 2kHz sampling (total body length : Max. 750mm)

X3: 3kHz sampling (total body length : Max. 600mm)

X4: 3.75kHz sampling (total body length : Max. 450mm)

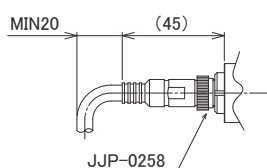
⑨ Clamp

F50 : with fixing clamps

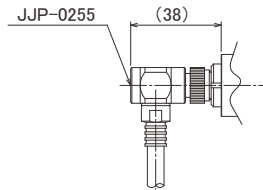
N : without fixing clamps

【Cable connection】

■ Connector type (straight) (STD)



■ Connector type (L-shaped) (option)



■ Pigtail type (option)

